

D'Alembert–Liouville–Ostrogradskii formula and related results

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Results, that generalize previous important results of the d'Alembert–Liouville–Ostrogradskii formula type by F.S. Rofe-Beketov, are obtained. The $2p \times 2p$ fundamental solution of the first order system is recovered by its $2p \times p$ block Y_0 . Applications to the asymptotics of the continuous analogs of polynomial kernels and to the pseudo-Hermitian quantum mechanics are treated. Similar to the F.S. Rofe-Beketov results the invertibility of the $p \times p$ blocks of Y_0 on the interval is not required.

1. Introduction

Suppose y_0 satisfies Sturm–Liouville equation $-y'' + qy = \lambda y$ ($y' = \frac{dy}{dx}$). Then the well-known D'Alembert–Liouville–Ostrogradskii formula

$$y(x) = y_0(x) \int_0^x y_0(\xi)^{-2} d\xi$$

gives another solution of the Sturm–Liouville equation. (See [2] for this formula and its matrix generalization.) Further developments and interesting applications

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to the spectral theory have been obtained in [4–6] and references therein. Two separate cases have been treated by F.S. Rofe-Beketov in [4–6]: canonical system

$$w'(x, \lambda) = i\lambda JH(x)w(x, \lambda) \quad (\lambda = \bar{\lambda}, \quad H = H^*, \quad J = \begin{bmatrix} 0 & I_p \\ I_p & 0 \end{bmatrix}) \quad (1.1)$$

with $m \times m$ Hamiltonian H , and non-self-adjoint system

$$w'(x, \lambda) = G(x, \lambda)w(x, \lambda) \quad (1.2)$$

with 2×2 matrix function G . Here $m = 2p$ and I_p is $p \times p$ identity matrix. It is essential to mention that the invertibility of given y_0 (or $p \times p$ block of the fundamental solution w) on the interval that is required in the initial D'Alembert–Liouville–Ostrogradskii formula (1) (or subsection 4.3 [2]) is not required in the formulas in [4–6] anymore.

In this note we shall consider a slightly more general first order system that includes systems (1.1) and (1.2) as well as a class of pseudo-Hermitian systems of m equations, in particular. Applications to the asymptotics of the continuous analogs of polynomial kernels and to the pseudo-Hermitian quantum mechanics will be treated. Similar to the F.S. Rofe-Beketov results the invertibility of the $p \times p$ block of the given $2p \times p$ solution on the interval is not required.

We denote by \mathbb{R} the real axis and by $\bar{\lambda}$ the complex conjugate to λ scalar (or the matrix with the complex conjugate entries).

The authors are grateful to F.S. Rofe-Beketov for introduction to this topic and very fruitful discussion.

2. Main theorem

Theorem 2.1. *Suppose $m \times p$ ($m = 2p$) matrix functions Y_0 and \tilde{Y}_0 satisfy systems*

$$Y_0'(x, \lambda) = G(x, \lambda)Y_0(x, \lambda), \quad \tilde{Y}_0'(x, \lambda) = \tilde{G}(x, \lambda)\tilde{Y}_0(x, \lambda), \quad (2.1)$$

where G and \tilde{G} are $m \times m$ locally summable matrix functions. Fix also an absolutely continuous $m \times m$ matrix function $D(x)$ and suppose additionally that

$$\det Y_0^* Y_0 \neq 0, \quad \det \tilde{Y}_0^* D \tilde{Y}_0 \neq 0, \quad \tilde{Y}_0^* Y_0 \equiv 0. \quad (2.2)$$

Then the matrix function

$$Y(x, \lambda) = Y_0(x, \lambda)g_0(x, \lambda) + D(x)\tilde{Y}_0(x, \lambda)\tilde{g}_0(x, \lambda), \quad (2.3)$$

where $p \times p$ matrix functions g_0 and \tilde{g}_0 are given by the equations

$$\tilde{g}_0' + (\tilde{Y}_0^* D \tilde{Y}_0)^{-1} \tilde{Y}_0^* (D' + D \tilde{G} - GD) \tilde{Y}_0 \tilde{g}_0 = 0, \quad (2.4)$$

$$g'_0 + (Y_0^* Y_0)^{-1} Y_0^* \left((D' + D\tilde{G} - GD)\tilde{Y}_0 \tilde{g}_0 + D\tilde{Y}_0 \tilde{g}'_0 \right) = 0, \quad (2.5)$$

satisfies the first system in (2.1) also:

$$Y'(x, \lambda) = G(x, \lambda)Y(x, \lambda). \quad (2.6)$$

P r o o f. The proof is straightforward. Indeed, by (2.1) and (2.3) we have $Y' = GY_0 g_0 + Y_0 g'_0 + (D\tilde{Y}_0 \tilde{g}_0)' = GY + (D' + D\tilde{G} - GD)\tilde{Y}_0 \tilde{g}_0 + D\tilde{Y}_0 \tilde{g}'_0 + Y_0 g'_0$. Therefore (2.6) is equivalent to the equality

$$(D' + D\tilde{G} - GD)\tilde{Y}_0 \tilde{g}_0 + D\tilde{Y}_0 \tilde{g}'_0 + Y_0 g'_0 = 0. \quad (2.7)$$

In view of the first and second relations in (2.2) we have $\det Z \neq 0$, where

$$Z(x, \lambda) := \begin{bmatrix} \tilde{Y}_0(x, \lambda)^* \\ Y_0(x, \lambda)^* \end{bmatrix}. \quad (2.8)$$

So we multiply both sides of (2.7) by Z and taking into account the third relation in (2.2) we see that (2.7) is equivalent to the equations (2.4) and (2.5). Thus (2.6) holds. ■

3. Examples

3.1. In the Subsections **3.1**, **3.2** we shall consider a particular case

$$D = I_m, \quad \tilde{G}(x, \lambda) = -G(x, \lambda)^*, \quad \tilde{Y}_0(0)^* Y_0(0) = 0. \quad (3.1)$$

Corollary 3.1. *Suppose G and \tilde{G} are locally summable in the interval $\Gamma \subseteq \mathbb{R}$ ($0 \in \Gamma$). Let equalities (2.1) and (3.1) hold and assume that*

$$\det Y_0(0)^* Y_0(0) \neq 0, \quad \det \tilde{Y}_0(0)^* \tilde{Y}_0(0) \neq 0. \quad (3.2)$$

Then relations (2.2) hold and matrix function

$$Y(x, \lambda) = Y_0(x, \lambda)g_0(x, \lambda) + \tilde{Y}_0(x, \lambda)\tilde{g}_0(x, \lambda), \quad (3.3)$$

where

$$\begin{aligned} \tilde{g}_0(x, \lambda) &= (\tilde{Y}_0(x, \lambda)^* \tilde{Y}_0(x, \lambda))^{-1}, \quad g_0(x, \lambda) = \int_0^x (Y_0(\xi, \lambda)^* Y_0(\xi, \lambda))^{-1} \\ &\quad \times Y_0(\xi, \lambda)^* (G(\xi, \lambda) - \tilde{G}(\xi, \lambda)) \tilde{Y}_0(\xi, \lambda) (\tilde{Y}_0(\xi, \lambda)^* \tilde{Y}_0(\xi, \lambda))^{-1} d\xi, \end{aligned} \quad (3.4)$$

satisfies (2.6).

P r o o f. The first two relations in (2.2) are immediate from (2.1) and (3.2). From (2.1) and the second relation in (3.1) it follows that $(\widetilde{Y}_0^* Y_0)' \equiv 0$. So in view of the third relation in (3.1) we get the third relation in (2.2). Therefore the conditions of Theorem 2.1 are fulfilled. As $D = I_m$ and $-G = \widetilde{G}^*$ one easily checks that \widetilde{g}_0 given by (3.4) satisfies (2.4). Using this and $Y_0^* \widetilde{Y}_0 \equiv 0$, we derive that g_0 given by (3.4) satisfies (2.5). Hence Y constructed in this corollary satisfies conditions of Theorem 2.1, i.e., equality (2.6) is proved. ■

Corollary 3.1 includes the case of system (1.1). In this case we assume

$$Y_0(0)^* Y_0(0) > 0, \quad Y_0(0)^* J Y_0(0) = 0. \quad (3.5)$$

According to the second relation in (3.1) and (3.5) we can put here $\widetilde{Y}_0 = J Y_0$. For the canonical system with $H \geq 0$ and $\Im \lambda < 0$ the asymptotics of the forms $Z(x, \lambda) J Z(x, \lambda)^*$ (analogs of the polynomial kernels) have been studied in [7]. The asymptotics of Z in the almost periodic case is based on formula (3.3) (see Theorem 6.2 [6]). From Theorem 6.2 [6] follows

Corollary 3.2. *Suppose Hamiltonian H and $m \times p$ solution Y_0 of system (1.1) are uniformly almost periodic on \mathbb{R} and (3.5) holds. Then for Z of the form (2.8), $\lambda = \bar{\lambda}$ and $|x| \rightarrow \infty$ we have*

$$\begin{aligned} & Z(x, \lambda) J Z(x, \lambda)^* \\ &= T(x, \lambda) \begin{bmatrix} Y_0(x, \lambda)^* Y_0(x, \lambda) & \mathbf{0} \\ \mathbf{0} & (Y_0(x, \lambda)^* Y_0(x, \lambda))^{-1} \end{bmatrix} T(x, \lambda), \end{aligned} \quad (3.6)$$

where $T(x, \lambda) = \begin{bmatrix} (K(\lambda) + o(1))x & I_p \\ I_p & \mathbf{0} \end{bmatrix}$,

$$K(\lambda) = K(\lambda)^* = \lim_{|x| \rightarrow \infty} x^{-1} g_0(x, \lambda).$$

3.2. Non-self-adjoint PT-symmetric and pseudo-Hermitian systems are actively studied last years following the important paper [1] (see further references in [3, 8]). Operator \mathcal{H} is called pseudo-Hermitian if $\mathcal{H}^* = \eta \mathcal{H} \eta^{-1}$, where operator η is a Hermitian invertible linear operator [3]. Putting $\eta = CP$, where $C = C^*$ is $m \times m$ matrix and $(Pf)(x) = f(-x)$, we see that system

$$w'(x) = i\lambda H(x)w(x, \lambda) \quad (x \in \mathbb{R}, \quad \lambda = \bar{\lambda}) \quad (3.7)$$

is pseudo-Hermitian if the locally summable $m \times m$ matrix function H satisfies equality

$$H(x)^* = -CH(-x)C^{-1}. \quad (3.8)$$

Corollary 3.3. *Suppose $m \times p$ matrix function Y_0 satisfies pseudo-Hermitian system (3.7), (3.8) and relations*

$$Y_0(0)^*Y_0(0) > 0, \quad Y_0(0)^*CY_0(0) = 0 \quad (3.9)$$

hold. Put also

$$\tilde{Y}_0(x, \lambda) = CY_0(-x, \lambda). \quad (3.10)$$

Then the conditions of Corollary 3.1 are satisfied.

3.3. If system (1.2) with 2×2 matrix function G is given, we put in Theorem 2.1 $p = 1$,

$$\tilde{G} = jJ\bar{G}Jj, \quad \tilde{Y}_0 = jJ\bar{Y}_0, \quad (3.11)$$

$$j = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad D(x) = \begin{bmatrix} 1 & 0 \\ 0 & \varphi(x) \end{bmatrix}. \quad (3.12)$$

Equality $\tilde{Y}_0^*Y_0 \equiv 0$ is now fulfilled automatically, and Theorem 6.6 [6] follows. System (1.1) includes the case of the self-adjoint Sturm–Liouville system and system (1.2) includes non-self-adjoint Sturm–Liouville scalar equation. D’Alembert–Liouville–Ostrogradskii formula for the Sturm–Liouville case may prove useful to judge on the existence of the subordinate solutions in the framework of the Gilbert–Pearson theory.

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